Tanner Declaration Exhibit B

TANNER SOFT

WinLok 2.0

Digital Model Railroad Command Control Software for Windows

Address information to: Digi RR Enterprises, 10395 Seminole Blvd.# E Seminole, FL, 34648

Introduction:

WinLok 2.0 is a Windows 3.1 based program to control digital equipped Model-railroad systems with the computer.
This Version supports following Digital Command Systems:

From Serial Port:

- **Arnold Digital & Märklin Digital =**
- **Märklin Digital**
- **Märklin 80f** ..... support of 4 functions (crane, turntable, dancecar etc.)
- **ZIMO**
- **Trix-Selectrix**
- **DirectDrive** ..... Supporting the NMRA DCC digital packet format. NMRA F7 or F8 Booster. Use full **DIGITRAX** decoder capability with DB100 , 14,28 and 128 Speed-steps. It will program and support following loco-decoders simultaneously: Any **DIGITRAX** with 1 to 3 functions, Lenz LE100S,-R / Lenz LE100M, Märklin c82 with 4 functions and ARNOLD

- **Digitrax LocoNet ™ Bus** allows simultaneous operation of WinLok as "dispatcher" and handhold throttles for the engineers. Great for multiple person operation and club-layout.

From Parallel Port:

- **Digit 99** The low cost, Do it yourself System. By Wolfgang Horn of Modellbahn Elektronik.

MULTIDRIVE..... Operate any of the above Digital Command Systems simultaneously. Requires one RS232 Serial Port and/or Parallel Port, and the appropriate booster and/or Command Control equipment for each system.

A.2.6. Test-Driver

The Test Driver serves the purpose of testing the operation of WinLok without the need to hook up to a interface and digital-system. Furthermore all driver-specific data can be changed to simulate any digital-system.
See figure A.2.6.1. Driver Data Input.

Set-up Driver Data

By clicking on this bar you open a new window for input of data specific to your digital system. Enter data with the keyboard and mouse.

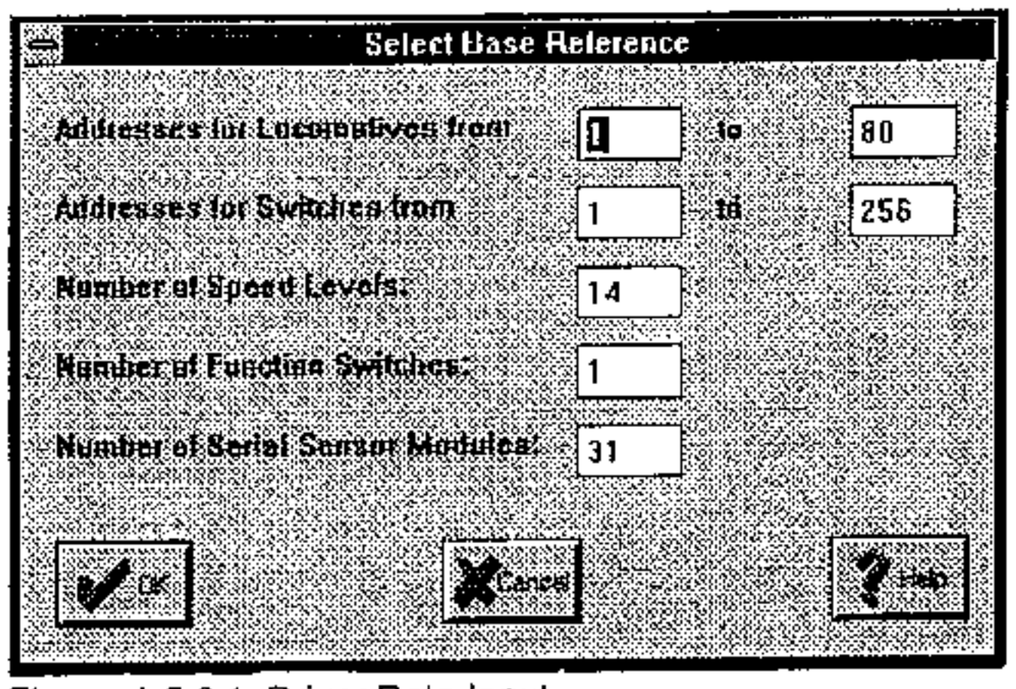


Figure A.2.6.1 Driver Data Input

Enter all data correct (consult the manual of your digital model railroad system for capacity and hardware specifics) to ensure the proper function.

All data will be loaded and corresponding devices adjusted by WinLok when the track-power is turned ON the next time.
About TannerSoft
Displays information, trademark and/or copy-protection etc.

A.2.7 TannerSoft MultiDrive

The TannerSoft MultiDrive provides the capability to control multiple digital model-railroad systems simultaneously. This enables for example, to operate a HO Mainline and a HOm logging RR with different systems. Or HO 3rail main and foreground while at the same time controlling a N scale background system. There are many combinations possible. Addresses may be defined free for each system and will then be translated into actual possible addresses.

A.2.7.1 Driver pull-down menu.

The WinLok Menubar displays the selected driver with the manufacturers logo.

DRIVER ALLOCATION
ABOUT MULTIDRIVE

A.2.7.2 Driver allocation

By clicking on this bar you open a new window for input with the keyboard and mouse.

Driver.... Select the driver you wish to change the addresses for this purpose.

From WinLok addresses: Enter in these six fields the addresses of the locos, Solenoid devices and Feedback-sensors you like to have controlled by the selected driver. Make sure that no addresses are overlapping to an other driver since these addresses must be unique. Overlapping addresses will make corresponding drivers to react and can cause confusion and will result in faulty commands and errors.

To Driver addresses: No input is possible here. These actual min. and max values are read from the selected driver data and can not be exceeded. If you for example, enter 90 Loco addresses with a Marklin driver, the invalid addresses will be ignored.

Example:

You have a layout with a Digitrax Mainline and a Arnold HOm sideline which you like to control with WinLok simultaneously. Your PC also has two free RS232 ports available.

Install the MultiDrive with these two "Subdrivers" DirectDrive and Arnold Drive.

Important: You need the appropriate Command Control or Booster for each system connected to a different Com-port. Since you already use the Mouse, most likely on Com-1 and a modem on Com-3 , you can use Com-2 and Com-4 which will possibly require the installation of a additional I/O Board with a minimum of one RS 232 connector.

Now set the addresses as follows:

Addresses Arnold drive:

WinLok	1	99	1	256	1	31
System	1	99	1	256	1	31

Addresses DirectDrive (DIGITRAX)

WinLok	101	199	257	512	32	62
System	1	99	1	256	1	31

This address setup results in controlling your HOm Arnold sideline with Loco addresses 1 - 99 while your Digitrax Mainline Locos respond to addresses from 101 to 199, yet there physical address is also 1 - 99. The same works with the solenoid decoders and feedback-modules.

Note: You don't have to fully extend each drivers address capacity. You could use Loco 1 - 20 from Arnold and Loco 21 - 40 with Digitrax. Just keep the possibility in mind, that a later expansion may require adjustment.

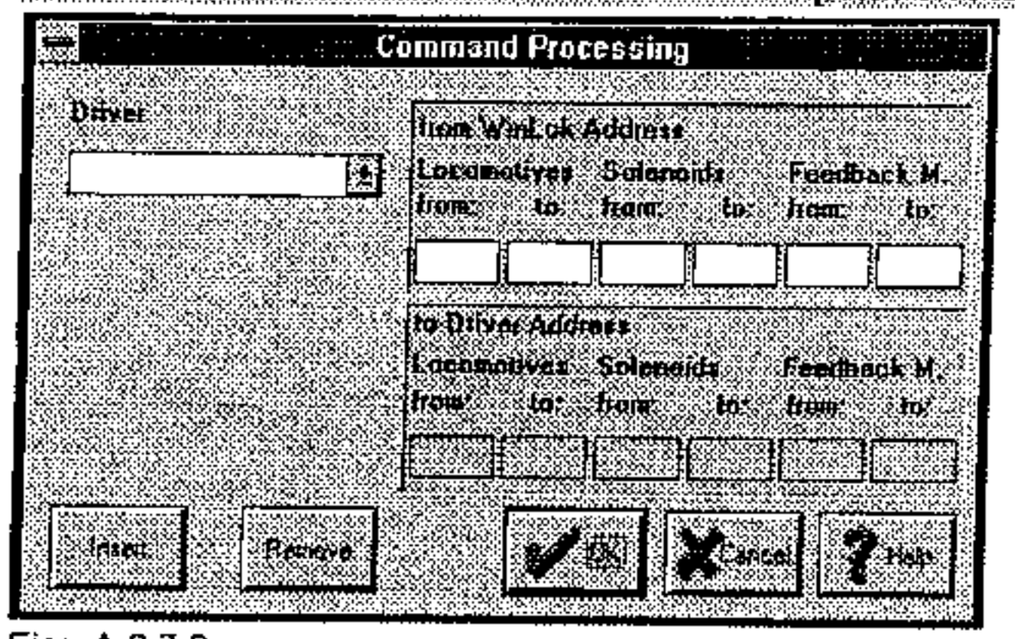


Fig: A 2.7.2

Insert: After clicking this button, a new box opens, displaying all available drivers for your selection. Highlight and click the OK button and the driver will be installed immediately and changes the WinLok menu accordingly.

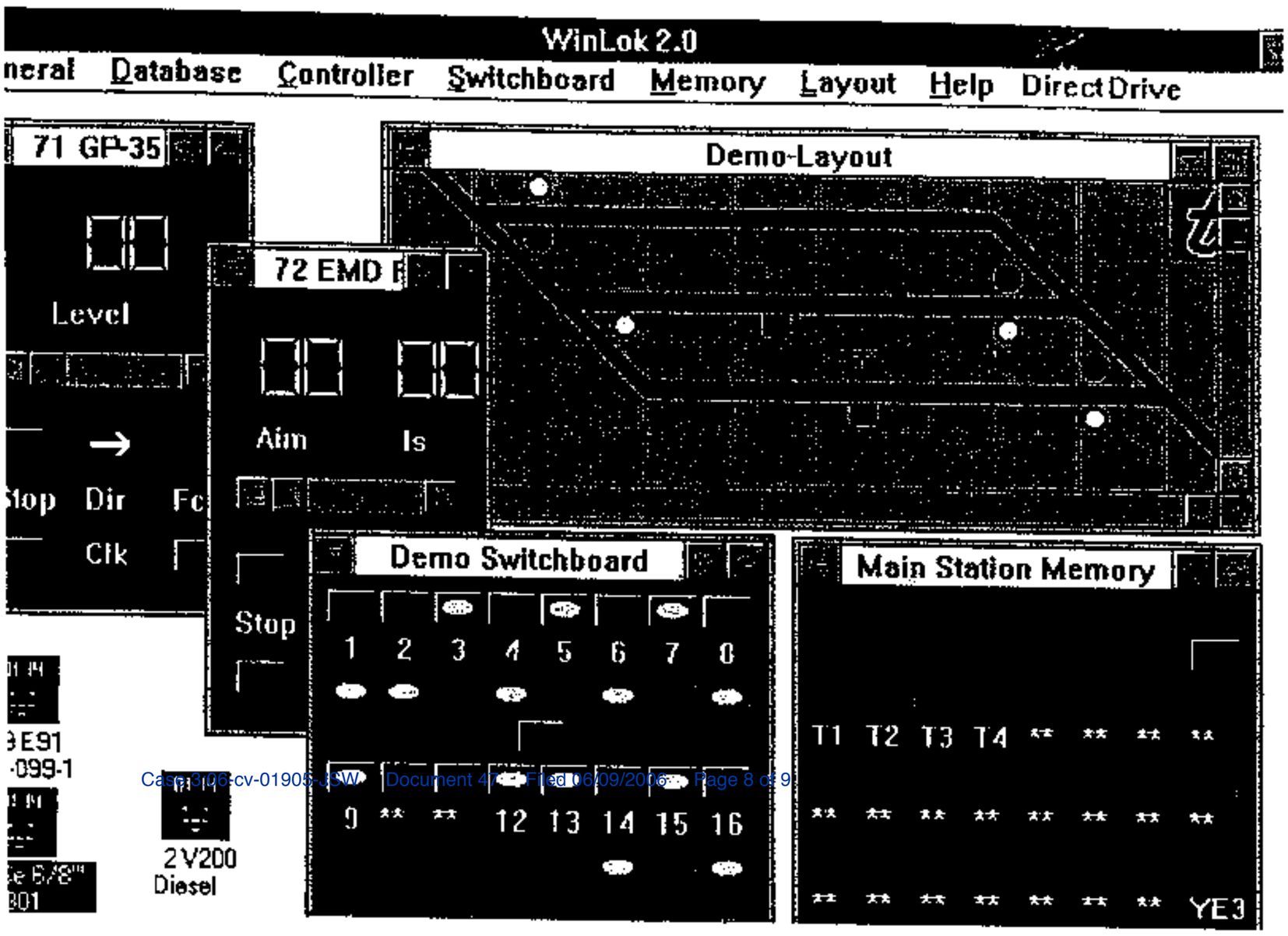
Delete: Click on delete and the highlighted driver is deleted from MultiDrive. The address setup is saved and comes up with the next installation of the driver in MultiDrive.

A.2.7.3 About MultiDrive

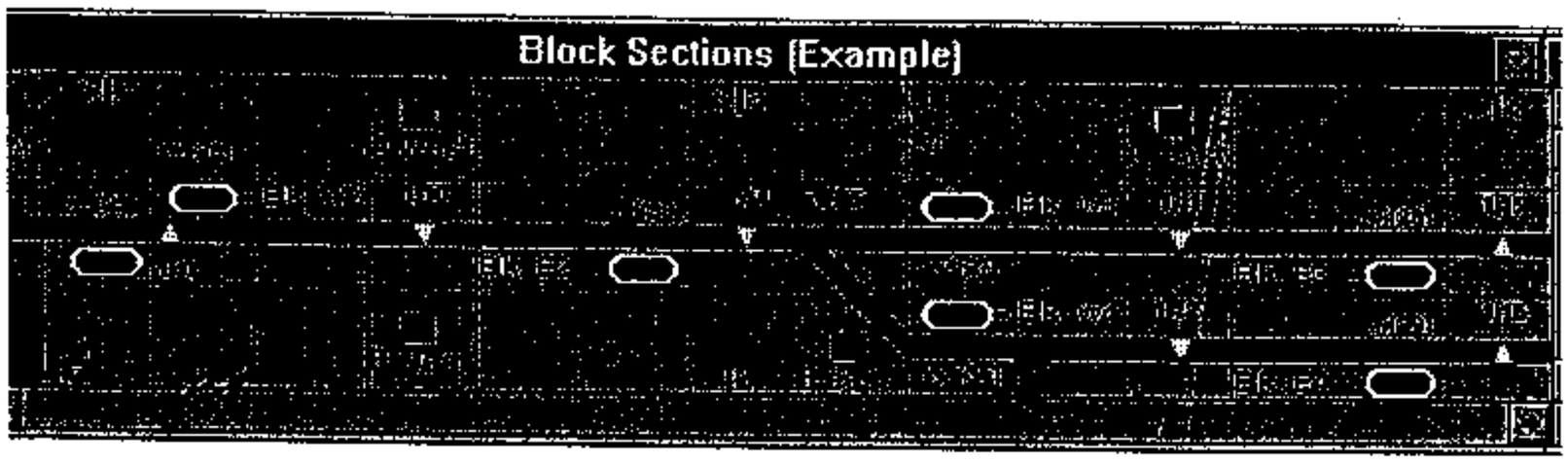
Displays information, trademark and/or copy-protection etc.

WinLok 2.0 © by TannerSoft

Digital Command Control Software for Windows



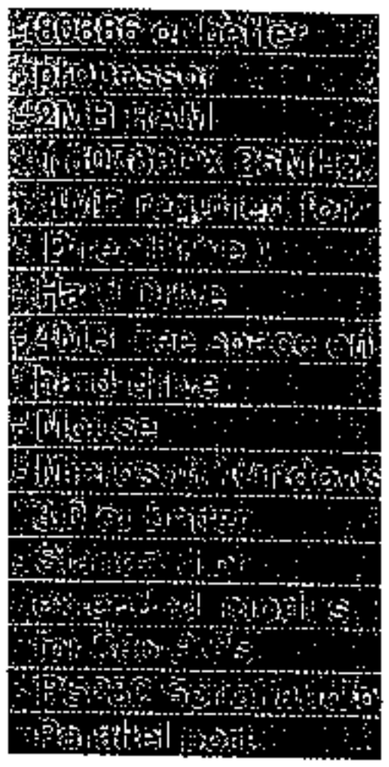
The New Dimension in Model Railroading



WinLok 2.0©

System-requirements.

WinLok 2.0 requires a IBM compatible PC with the following minimum configuration:



And for your Model Railroad:
One of the following Digital Command Control Systems:

Digitrax
LENZ
Arnold
NMRA DCC
märklin
TrixSelectrix
Zimo

Contains one 3.5" Floppy and Documentation

2.0©

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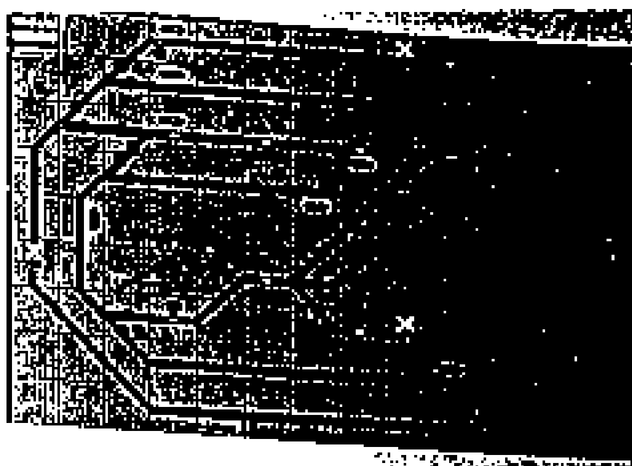

WinLok 2.0
for Windows

NMRA Dcc compatible

Introduction:

The software for the serious Model railroad and computer enthusiasts that allows realistic operation of a layout with the aid of the computer to control all switches, routes and block occupation, displayed on individually created CTC panels for each yard or section as desired. Run trains with on screen throttles or use handheld throttles simultaneous if selected command control system provides interface (Digitrax LocoNet-Bus, Lenz X-Bus, Märklin 6050 interface with central unit and control 80 or 80f).

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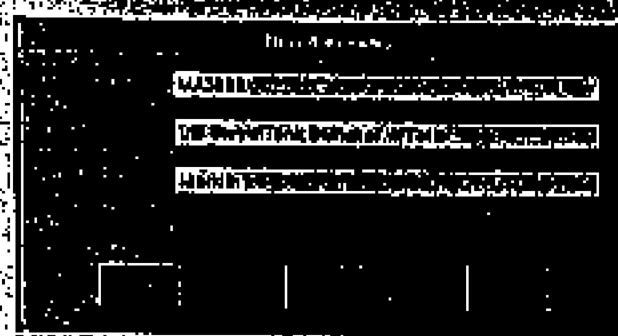

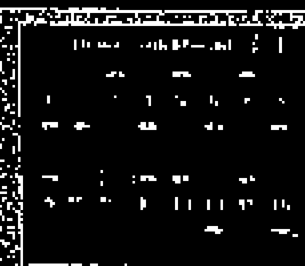

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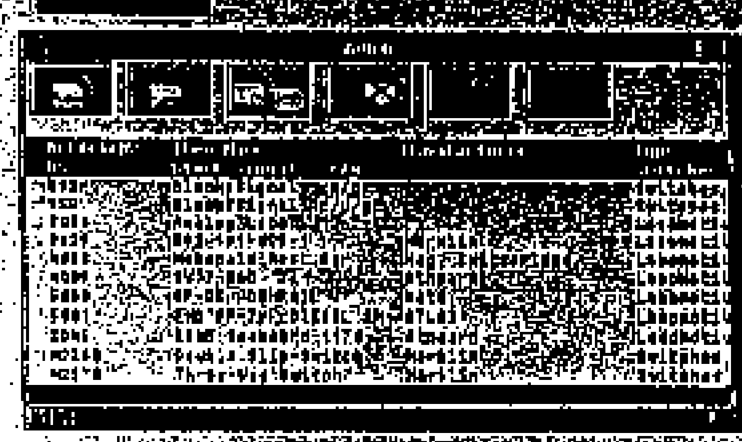

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DIGITRAX

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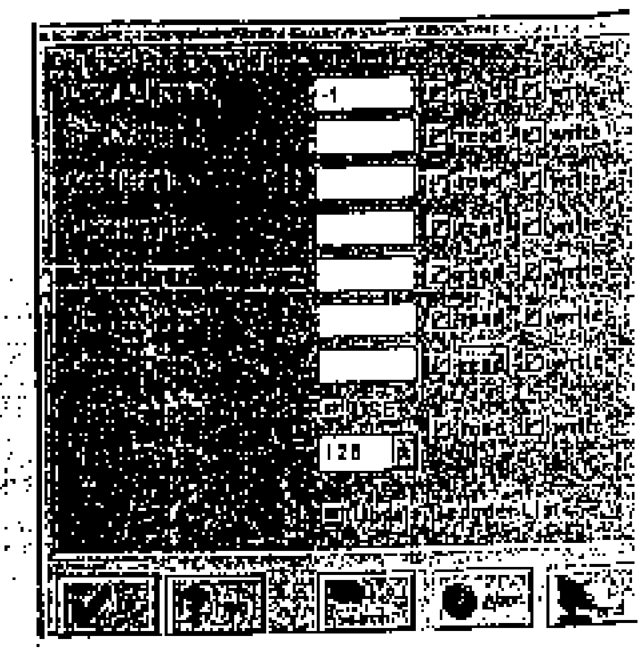

Lenz X-Bus will basically perform the same as above.

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- **Digit 99** The low cost, Do It yourself System By Wolfgang Horn of Modellbahn Elektronik.

MULTIDRIVE Operate any of the above Digital Command Systems simultaneously. Requires one RS232 Serial Port and/or Parallel Port and the appropriate booster and/or Command Control equipment for each system.

Features of WinLok 2.0

- [illegible] digital control devices such [illegible] Switchboard and Memory with all [illegible]
- [illegible] track diagrams (entire layout or sectional) with [illegible], indicator lights and text
- [illegible] turnouts, signals and [illegible] with the click of the mouse
- [illegible] block sections and hidden yards
- [illegible] ONE STEP decoder programming feature for Digitrax, Lenz, Arnold and Märklin
- [illegible] program (functions, accelerate and [illegible]) after power up of layout
- Multiple [illegible] with same controller
- [illegible] routes allocation on switchboard and memory
- [illegible] delays and default settings for solenoid [illegible]
- [illegible] programming
- Automated operation possible simultaneous with manual operation
- Support of parallel (8255 based) interface cards for faster [illegible] with sensor modules
- The amount of devices used is only limited by the memory of the computer system being used
- User friendly, easy to learn program in WINDOWS environment and completely mouse supported
- [illegible] support of up to 255 speed settings and 16 functions
- High flexibility in selection of drivers for the operation of different Digital Model Railroad Systems